

Batteryless Encapsulated Hydrometer

Design Document

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SDDEC20-06

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Executive Summary

Development Standards & Practices Used

- Kicad for schematic layout and PCB design
- FreeCAD for housing and mechanical layout and design
- Waterproof and food safe housing capable of IP68 rating standards

Summary of Requirements

- Wirelessly powered
- Batteryless
- Food safe
- Wirelessly transmit readings with a minimum frequency of hourly
- Measure the specific gravity of the fluid
- Measure the temperature of the fluid
- Completely encapsulated

Applicable Courses from Iowa State University Curriculum

- EE285
- EE303
- EE452
- EE333
- EE201
- EE230
- IE305
- EE311
- PHYS221

New Skills/Knowledge acquired that was not taught in courses

- Wireless power transfer using matched antennas
- Bluetooth communications on embedded systems
- Tilt hydrometer design and implementation

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1 Introduction

1.1 ACKNOWLEDGEMENT

We would like to acknowledge Assistant Professor Henry Duwe for his contributions towards our technical design. Professor Duwe works at Iowa State University and focuses on computing and networking systems for secure and reliable computing. One of his current research areas concentrates on wireless energy harvesting and limitations associated with onboard functionality. His research in this area has provided us with groundwork information that is fundamental in the performance of our design. He has also overseen all the individual research that our team has compiled throughout this project. We would also like to acknowledge our client Duwe Amalgamated Research Corporation for their sponsorship in this project.

1.2 PROBLEM AND PROJECT STATEMENT

In the past decade researchers have been exploring the many facets of wireless energy harvesting. In this process an RF signal is used to wirelessly transmit power to a designated electronic platform. This platform uses either a re-chargeable battery or capacitor to store and distribute the signal energy. Many embedded computational systems are beginning to take advantage of this developing technology but there are many issues surrounding its implementation. Such issues include limited power transfer, signal reception quality, signal strength, etc.

Our project will expand the capabilities of these embedded computational systems and reduce some of the limitations associated with wireless power transfer. To achieve this goal, we will develop a device that can measure the specific gravity within an enclosed container with one hundredth precision. The device will be powered wirelessly by a commercially produced PowerCast transmitter (tx91501b) at 915Mhz. It will remain unpowered until the onboard capacitor has charged to a voltage release point. The stored power will be distributed using an appropriate hysteresis model to power onboard instrumentation. The device will also transmit the collected data wirelessly to a collection device. The commercial intent of this system is to supply home brewing hobbyists/enthusiasts with a better way to monitor the quality and control of their fermentation process.

1.3 OPERATIONAL ENVIRONMENT

The intended operational environment for our design is a completely enclosed stainless-steel fermentation tank. This environment is inclusive of high temperatures and liquid exposure. Some of the fundamental aspects to the mechanical portion of our design consists of complete encapsulation(watertight) and temperature resistivity. Other suitable environments for our platform include aquariums, ponds, or any other enclosed liquid environment.

1.4 REQUIREMENTS

The following requirements have been assigned to this project via Duwe Amalgamated Research Corporation:

1. The transmission signal must be strong enough to travel 2ft beyond the exterior walls to span the diameter of the fermentation tank.
2. The transmission signal must charge an onboard capacitor within a days' time without losing signal quality.
3. The transmission signal must provide enough power for consistent data collection and transmission.
4. The data signal must be able to transmit within the fermentation tank and possibly submersed in liquid.
5. The design must be completely encapsulated and smooth. This will protect onboard electronics and eliminate access for bacteria to collect on the design during fermentation.
6. The design must be temperature resistant. Fermentation temperatures may affect the measurements from onboard electronics.

Any failure to meet of these requirements must be addressed to the client Duwe Amalgamated Research Corporation.

1.5 INTENDED USERS AND USES

The intended end user is **the client**, Duwe Amalgamated Research Corporation, for measuring a potentially changing specific gravity of a liquid within a sealed container. The sealed liquid container will not be made of metal as that interferes with wireless transmissions.

1.6 ASSUMPTIONS AND LIMITATIONS

Assumptions:

1. Most calculations shall be done on the base station to maximize expandability.
2. The end product will operate within a temperature range of 50°F to 80°F.
3. The specific gravity measurement should be within 1% margin of error.
4. The end product will only need to transmit data once per hour.

Limitations:

1. The end product cost of production shall not exceed \$140 (client requirement).
2. The end product length shall not exceed 12" (client requirement).
3. The end product must be fully encapsulated (client requirement).
4. The end product should be able to operate for years without intervention (client requirement).
5. The end product must be able to wireless transmit data to a collection device (client requirement).
6. The system shall not use a battery (client requirement).

1.7 EXPECTED END PRODUCT AND DELIVERABLES

The expected end product deliverable should be a prototype, fully encapsulated, batteryless hydrometer using a custom PCB. Included with this is the code for our desired base station to communicate with the hydrometer and an analysis of the hydrometer's lifetime reliability. These are to be delivered by November 27th, 2020.

2. Specifications and Analysis

2.1 PROPOSED APPROACH

We will start the design approach by splitting into 2 main teams, a hardware team and software team. The hardware team has been researching the energy harvesting technology as well as some antenna design for sending. The software team has been researching the best option for a base station and researching the what the best low power communication protocol would be for our application.

We plan on having a functional prototype by the end of the semester. This includes a custom PCB that has energy harvesting capabilities, an accelerometer, a temperature sensor, and a microprocessor. We will also need to have a base station that can receive data from the hydrometer.

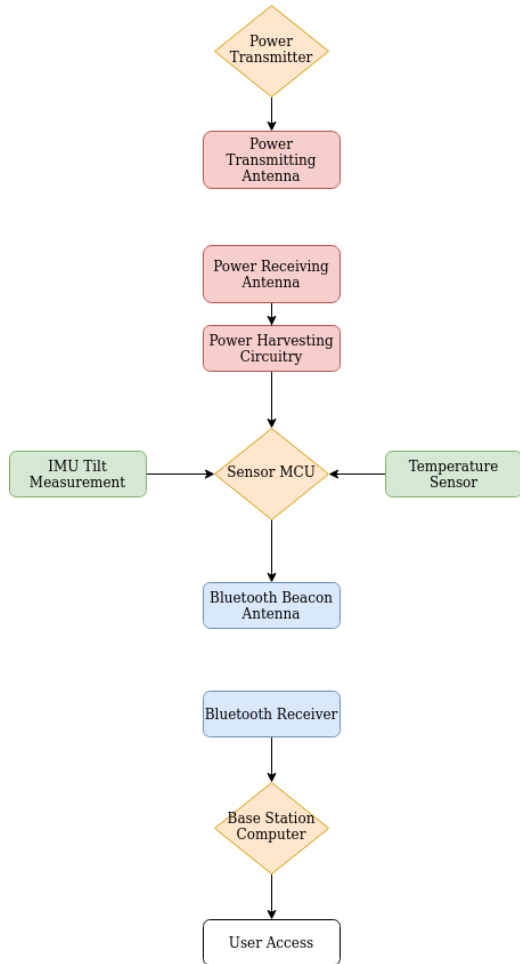
2.2 DESIGN ANALYSIS

As discussed above, we have mostly done research up to this point. We will soon begin experimenting with the energy harvesting and working on code for the microcontroller and base station. We decided to use a raspberry pi for the base station because of the Bluetooth and WIFI capabilities.

2.3 DEVELOPMENT PROCESS

For the mechanical design, we will be using either Solid Works or FreeCAD. For the PCB design, we will be using KiCad. For the Firmware and software, we will be using an SDK from Silicon Labs (Simplicity Studio 4) and the IDE on the Raspberry PI.

2.4 CONCEPTUAL SKETCH



3. Statement of Work

3.1 PREVIOUS WORK AND LITERATURE

There is a product called Tilt Digital Hydrometer and thermometer that has the same functionality we are attempting to achieve. The device allows users to wirelessly read specific gravity and temperature. Specific gravity is measured using an accelerometer on this device. The device is powered with a battery.

The hydrometer we will be developing will not use a battery. It will be able to take the readings that the Tilt hydrometer can take and will have wireless communication with a user interface. Because the hydrometer we have designed is battery less it will implement an energy harvester to wirelessly receive energy. This will mean less user maintenance.



Figure 1: Tilt Hydrometer

“The Tilt hydrometer lets you instantly read your brew's specific gravity and temperature on your compatible Apple iPhone/iPad or Android smartphone/tablet or Tilt Pi. Most Bluetooth 4.0+ devices will work with the Tilt.”¹ The Tilt hydrometer website tells us the hydrometer communicates with bluetooth.

“The specific gravity is accurate +/- 0.002 within the Tilt's range of 0.990 to 1.120. The thermometer is accurate +/- 1 degree F (+/- 0.5 degree C).”¹ The sensors have the accuracy previously listed.

3.2 TECHNOLOGY CONSIDERATIONS

“Q. How long will my battery last?”¹

“A. The lithium CR123A battery will last 3 months for our first generation models (blue-green circuit board) or 12 months for our second generation and later models (black circuit board). The second generation model will last 24 months in sleep mode.”¹

Our battery less hydrometer will not require the user to change the battery or track battery life.

3.3 TASK DECOMPOSITION

- Layout basic system diagram
- Determine sensors needed
- Select main MCU
- Determine mechanics of tilt system
- Select sensor components
- Design base station layout
- Determine base station hardware
- Write and test some code on ‘Gecko’ development board
- Gather data on power harvesting capabilities
- Design system schematic
- Design and order prototype PCB
- Determine how to fully encapsulate system
- Design the encapsulating housing
- Order prototype hardware
- Write prototype code
- Assemble prototype
- Test prototype
- Lessons learned and next steps

3.4 POSSIBLE RISKS AND RISK MANAGEMENT

The antenna that will be used for energy harvesting is 6 inches and we are not sure if it will work when it is submerged in water. 95% of the Tilt hydrometer is submerged in water so this may lead to some issues for our implementation. The cost of the energy harvesting circuit is also a concern. The price of our device needs to be around \$140 and we are concerned with this extra functionality driving up our cost. If the antenna cannot operate in water, we are concerned with how accurate our device will be with 6 inches of it above water.

3.5 PROJECT PROPOSED MILESTONES AND EVALUATION CRITERIA

Wireless Power Harvesting: Determine the environment that the device is capable of harvesting energy in (water, air, plastic shield, etc.).

Tasks:

- Confirm functionality of power harvesting circuitry in different environments

- Design power harvesting circuitry based on the designs provided by client

Tests:

- Transmit 915 MHz signal through empty plastic container (amount of time for LED to turn on)
- Transmit 915 MHz signal through plastic container with water (amount of time for LED to turn on)
- Based on the results of the above tests determine an optimal design for the power harvesting circuit

Power system function: Analyze the power supply circuitry of our circuit and determine the functional time our microcontroller will have to collect data, perform the necessary calculations, and transmit the data back to the user interface over Bluetooth. Determine the optimal voltages to switch the circuit on and off.

Tasks:

- Determine an optimal capacitor based on cycle life, charging time, and discharge rate

Tests:

- Measure the discharge rate of the capacitor
- Measure capacitor charging time

Microcontroller Function: After determining how much time the microcontroller will have to perform calculations, we may have to stagger functionality. For example, the first five times the microcontroller turns on it will collect data. The sixth and seventh times it will transmit the data to the user interface. The eighth time it may re-calibrate itself. Additionally, we need to consider the memory we need for the code.

Tasks:

- Determine microcontroller on/off functionality
- Determine the size of written code for calculations and sensor libraries

Tests:

- Cycle the microcontroller on and off and test functionality

Sensor Accuracy: In order to provide a device that is accurate the sensors may need to be calibrated. For example, if the temperature of the accelerometer increases this may affect the way that calculations must be done to determine an accurate position reading. The accuracy will also be heavily influenced by the mechanical design of the battery less hydrometer so before calibration can be finalized, we need to finalize the mechanical design.

Tasks:

- Calibrate Sensors

Tests:

- Test operation of the accelerometer in different temperature environments
- Test operation of the accelerometer in mechanical design

PCB Layout/Chip pinouts: Decide on IC's and associated circuitry that will be used for all functional areas of battery less hydrometer. Design circuitry and layout PCB of battery less hydrometer based on chosen IC pinouts and associated circuitry as well as desired mechanical functionality.

Tasks:

- Choose IC's
- Design circuitry (Simulate and test everything that is possible to)
- Layout PCB

Tests:

- Test individual IC's that are possible to test without PCB
- Test PCB functionality

Mechanical: The hydrometer must tilt based on the density of the liquid that it is in. This seemingly simple task will be quite challenging. We must consider weight, buoyancy, and the shape of the mechanical design.

Tasks:

- Design container

Tests:

- Test operation of the accelerometer in mechanical design

3.6 PROJECT TRACKING PROCEDURES

We will use the milestones discussed in the 3.5 as well as the Gant chart from 4.1.

3.7 EXPECTED RESULTS AND VALIDATION

The desired outcome is an accurate battery less hydrometer capable of energy harvesting that communicates data to the user using Bluetooth communication. The cost of this device needs to be below \$140.

Measurements displayed on the user interface will correspond to the temperature and specific gravity of the environment being used to test the battery less hydrometer.

4. Project Timeline, Estimated Resources, and Challenges

4.1 PROJECT TIMELINE

Spring 2020 Gantt Chart	Week Number															
Task	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Layout basic system diagram																
Determine sensors needed																
Select main MCU																
Determine mechanics of tilt system																
Select sensor components																
Design base station layout																
Determine base station hardware																
Write and test some code on 'Gecko' dev board																
Gather data on power harvesting capabilities																
Design system schematic																
Design and order prototype PCB																
Determine how to fully encapsulate system																
Design the encapsulating housing																
Order prototype hardware																
Write prototype code																
Assembly prototype																
Test prototype																
Review lessons learned and next steps																

In this timeline you can see that we will be focusing on making sure that we have developed sound solutions for our project before purchasing components and trying to build a prototype. Also, with this Gantt chart you can see that we progress methodically through the project and have planned out design and build timelines for different aspects of our project to finish at the same times. This will allow us to complete a first prototype by the end of the semester. This first prototype will halfway implement the sealed encapsulation but will likely be able to be disassembled for testing purposes.

Additionally, the specificity present in our Gantt chart will help us stay focused so that our project timeline can be stuck to during the spring 2020 semester. By sticking to this timeline, we will have an initial prototype tested by the end of this semester which will set us up with data and a prototype to improve during the fall 2020 semester. The current plans for next fall will be to take what we learn this spring with the prototype and create a fully sealed unit that cannot be disassembled, create a more streamlined and reliable physical design, and improve our power harvesting and software efficiency to create more frequent transmit cycles.

4.2 FEASIBILITY ASSESSMENT

From our investigations thus far, this project is feasible with a few key challenges. The main challenge will be harvesting enough power from the transmitter to consistently and reliably transmit data. This will be added to by the possibility of the sensor being placed in a metal tank which could make the power harvesting unfeasible in such an application. The other challenge will be properly designing the mechanics of the tilt aspect to ensure that the sensor tilts enough for highly accurate specific gravity measurements while also not restricting the power harvested. By taking into account these challenges we should be able to design around them to make our sensor feasible in most applications.

4.3 PERSONNEL EFFORT REQUIREMENTS

Task	Member Responsible	Effort Required
Layout basic system diagram	Jensen	Significant; but brief to get the layout done.
Determine sensors needed	Chris M.	Fair; effort to reconcile the diagram with available sensor types.
Select the main MCU	Griffin	Significant; due to the abundance of options.
Determine mechanics of the tilt system	Tilden	Very challenging; as there is little information available about it.
Select sensor components	Griffin	Fair; to determine the proper packages and specifications.
Design base station layout	Tilden	Significant; will be necessary to determine user needs.
Determine the base station hardware	Jensen	Fair; will require finding hardware to match the layout.
Write and test some code on 'Gecko' dev board	Josh	Significant; it will require writing custom Bluetooth beacon code.
Gather data on power harvesting capabilities	Griffin	Straightforward; but time consuming to collect data.
Design system schematic	Chris M.	Challenging; will need to take all parts and properly layout circuitry.
Design and order prototype PCB	Chris P.	Very challenging; will require very specific design choices.
Determine how to fully encapsulate the system	Tilden	Challenging; will require looking at novel manufacturing methods.
Design the encapsulating housing	Jensen	Significant; CAD tool for mechanical design will be learned.
Order prototype hardware	Chris P.	Straightforward; should be a matter of ordering the BOM from Kicad.
Write the prototype code	Josh	Challenging; will require highly efficient and fast code for the sensor.
Assembly prototype	Griffin	Challenging; we will be using some small chips creating risks.
Test prototype	Chris P.	Significant; may be easy or hard depending upon design success.
Review lessons learned and next steps	Full Team	Significant; this will be important for our overall success in the fall.

As can be seen in this table, I focused on tasks that are significant to very challenging for most of our Gantt chart. This encompasses the entirety of the project and helps us focus in upon the specific items that we can expect to struggle with. Knowing in advance that we will have challenges with certain tasks will allow us to prepare in advance to set us up for success in completing them.

4.4 OTHER RESOURCE REQUIREMENTS

Apart from financial resources we will need the following resources:

- Lab Access to the power harvesting development kits.
 - It is necessary to gather data on the power harvesting capabilities of these modules.
 - It will be extremely useful to have hands on experience with these modules before building them into our sensor.
- Equipment for building our sensor.
 - Our prototype and final designs will require the use of a reflow oven to properly construct.
 - To encapsulate the system, we will likely need a molding setup and a 3D printer to make a functionally accurate prototype.
- Time
 - We will need to make time available outside of our work schedules to contribute to this project.
- Software Access
 - We will be using Kicad for PCB design.
 - We will be using Solidworks or FreeCAD for the mechanical design.

4.5 FINANCIAL REQUIREMENTS

For our project we have the following cost estimate of what it will take to go from the initial design at this point to a final product at the end of next fall. These numbers are very rough at this point but will become fine-tuned as we get farther into the project.

Testing Hardware	\$30
Initial Prototype <ul style="list-style-type: none"> • PCB - \$15 • Electrical Components - \$100 • Housing - \$20 	\$135
Base Station with Power Transmitter	\$150
Miscellaneous	\$50
Project Total (Estimate)	\$365

5. Testing and Implementation

The batteryless, encapsulated hydrometer has numerous parts that need to work simultaneously for the product to function properly. This includes the mechanical tilt, measurement of the angle of tilt, computation, energy harvesting, and wireless communication back to the base station. In order to facilitate the success of this product, extensive testing will be necessary for each of the components.

5.1 INTERFACE SPECIFICATIONS

The major consideration with interfaces in this product is concerned with power consumption. In order to limit the power consumed, the communication between devices will need to be fast. A model of total time required to complete the communication in each cycle should be made.

- There will be serial communication via an I²C bus between the microcontroller and the accelerometer and temperature sensor. The functionality of this serial bus will need to be evaluated and modeled.
- There will be wireless communication with the base station via a connectionless Bluetooth transmission. The current consumption and time required to transmit should be measured. Additionally, the environment it will be transmitting from is near fluids which can limit signal integrity. The ideal transmission power (in dBm) should be selected based on test results.

5.2 HARDWARE AND SOFTWARE

The hardware for this product will exist on a printed circuit board (PCB) that hosts the embedded system. This will include the energy harvesting subsystem, the power management circuitry, the microcontroller and sensors, and the wireless communication subsystem. The software will include sensor data collection, calibration, computation, wireless communication, and an exit flag.

Hardware:

1. Energy Harvesting:
The product will utilize a PowerCast system that operates in the 915 MHz frequency band. The energy harvesting dipole antenna is designed by the PowerCast Corporation along with the P2110B PowerHarvester Receiver.
2. Power Management:
The power management circuitry exists on the P2110B module. Once the voltage across the capacitor reaches a selected value, the voltage regulator will be activated until either the voltage drops too low or the shutdown flag is activated.
3. Microcontroller and Sensing:
The microcontroller (MCU) selected for this product is the EFR32BG13. This product offers low power consumption along with fast boot times. Additionally, it has an integrated Bluetooth 5 physical layer (PHY) and 2.4 GHz transceiver. The sensors that will be selected will utilize an I²C serial bus for communication with the MCU. There is a 6-axis accelerometer and temperature sensor on the device which will be utilized in the calculation of the specific gravity of the current fluid to within ± 0.001 [g/cm³] accuracy.
4. Wireless Communication:

The wireless communication will utilize a connectionless Bluetooth session called a Bluetooth Beacon. In this configuration, the product will transmit the data at 2.4 GHz under the Bluetooth 5 protocol without connecting to the base station.

Software:

1. Sensor Data Collection:

The software will collect sensor data using the I²C protocol and existing libraries. The libraries used to access the sensor functions will be modified versions of existing code to minimize memory utilization on the device.

2. Calibration:

The calibration of the measurement data will be housed on the base station and not on the product. This will allow for the user to calibrate data in the field without accessing the PCB directly. This calibration process will be designed to be accurate to within ± 0.001 [g/cm³].

3. Computation:

The computation of the specific gravity will be performed on the base station. As a result, the hydrometer will transmit raw sensor data for calculation and calibration to be performed by the end-system.

4. Wireless Communication:

The wireless communication will be performed over a Bluetooth 5 Beacon and will require all relevant libraries to be stored in on-chip memory.

5. Exit Flag:

One of the pins on the MCU will be a dedicated exit flag that will kill the power to the microcontroller once all necessary operations have been completed. There is a pin on the P2110B module to perform this operation. This will allow for the power management circuitry to charge faster since the device will only consume the power it requires and not all available power.

5.3 FUNCTIONAL TESTING

1. Energy Harvesting:

The energy harvesting antenna and P2110B PowerHarvester Receiver will need to be profiled together for efficiency, gain, polarity, and power harvesting under various conditions.

2. Power Management:

An analysis of power consumption of the entire product will need to be made and adjustments to the activation threshold will need to be made. Additionally, an appropriate capacitor size will need to be selected to act as the power source for the product.

3. Microcontroller:

The microcontroller will be tested for startup time, power utilization during sensor measurement, power utilization during computation, and power utilization during Bluetooth transmission.

4. Wireless Communication:

The transmission will be characterized by measuring the transmission time and current consumption during transmission. Transmissions will also be tested for received data integrity under various conditions to determine the minimum transmission power level. Additionally, the RF impedance matching circuit will be analyzed to ensure that the impedance is within 5% of the required 50Ω impedance of the chip antenna.

5. Sensor Data Collection:

The sensors will be tested for wakeup time, measurement time, and power consumption during measurement and idle. Testing will also be done to ensure that full functionality is maintained through the reduction of the device libraries.

6. Calibration:

This calibration process will be designed to be accurate to within ± 0.001 [g/cm³] and verified through testing.

7. Wireless Communication:

The software will need to be ensured that it can fit into the on-device memory.

8. Exit Flag:

The exit flag must be tested to ensure that it operates as designed. An analysis should be performed to determine how much time and energy is saved from using the exit flag versus allowing the available power to be consumed.

5.4 NON-FUNCTIONAL TESTING

1. Performance:

The exit flag must be tested to ensure that it operates as designed. An analysis should be performed to determine how much time and energy is saved from using the exit flag versus allowing the available power to be consumed.

2. Compatibility:

The device should be tested to ensure that its Bluetooth 5 Beacon capabilities are compatible with previous versions of Bluetooth.

5.5 PROCESS

1. Power Consumption Tests:

A 1Ω resistor will be placed in series with a power supply and the microcontroller. The voltage across the resistor will be collected on an oscilloscope and stored in a .csv file. The voltage across the resistor is reflective of the current consumed during operation.

2. Transmission Power Level Testing:

The EFR32BG13 development board shall be placed in a watertight container and powered by a battery for this test. It will be programmed to transmit from 0 dBm to 19 dBm with increments of 1 dBm at a time. Received power will be measured from the base station in various environments including a fluid to introduce interference. The base station and transmitter shall be 1.5 meters apart. The minimum power level necessary without compromising signal integrity should be selected.

3. Startup/Wakeup Times:
TBD

5.6 RESULTS

We have not yet reached this phase as we are still in the design stage of our timeline.

6. Closing Material

6.1 CONCLUSION

With the project just getting kicked off, we have yet to make significant progress in prototyping. We have instead spent our time thus far accomplishing planning and design tasks to set out a specific and achievable plan for the rest of the semester that can smoothly carry over into next fall. Going forward we plan to begin testing with and collecting data with our development tools available to us and then we will get into the design and prototype phase as the semester goes on. This focus will be the best setup for allowing us to successfully have an initial working prototype at the end of this semester.

6.2 REFERENCES

- 1 <https://tilthydrometer.com>

6.3 APPENDICES

No further appendix information at this time.